

Grassmann and Flag Varieties in Linear Algebra, Optimization, and Statistics

An Algebraic Perspective

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based on joint work with Serkan Hoşten: arXiv 2505.15969

Flag Varieties

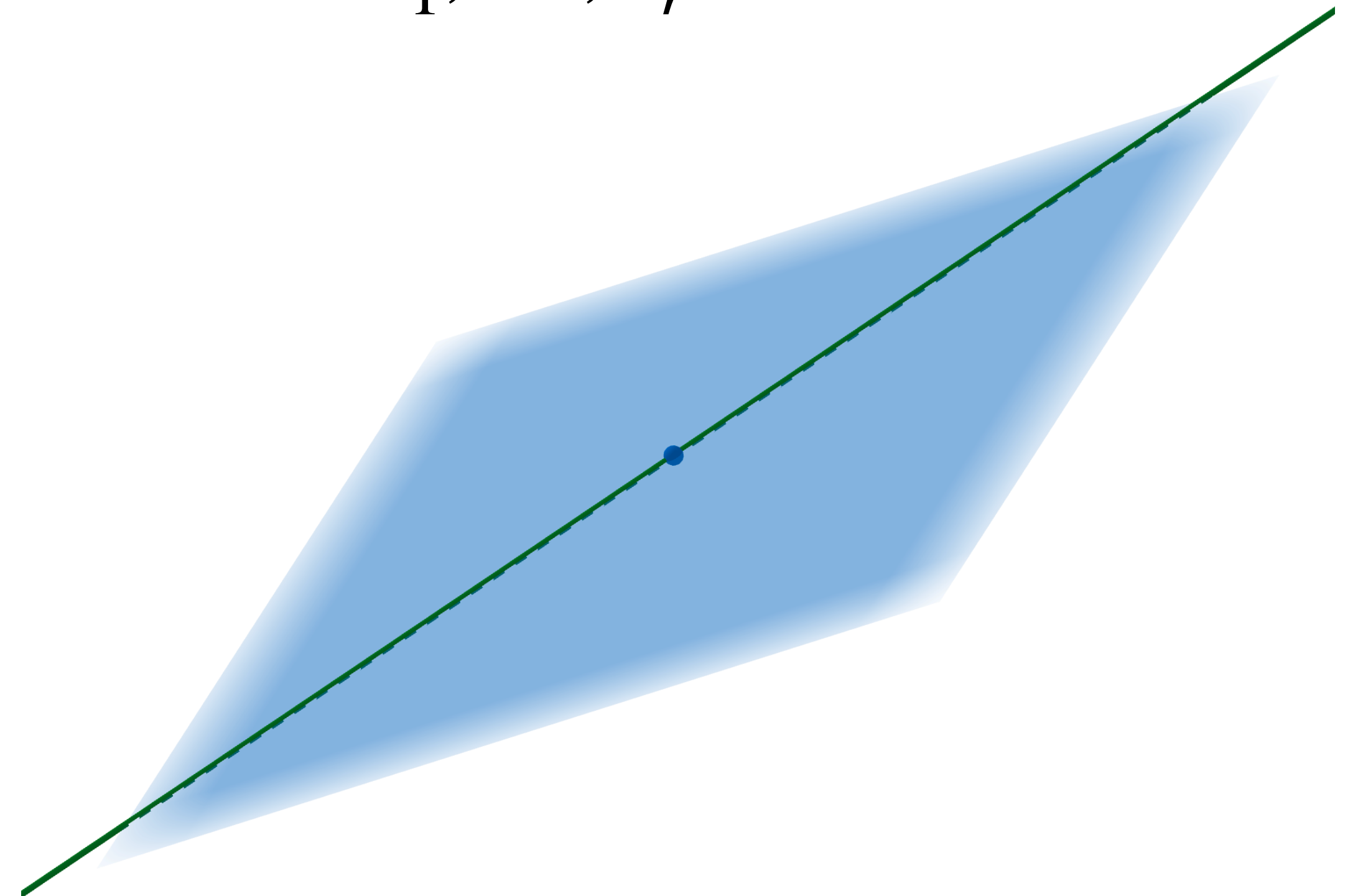
Definition. The flag manifold or variety

$$\mathrm{Fl}(k_1, \dots, k_r; n) = \{ W_1 \subseteq W_2 \subseteq \dots \subseteq W_r \subseteq \mathbb{R}^n : \dim(W_i) = k_i, i = 1, \dots, r \}$$

is the space of nested subspaces of dimension $k_1, \dots, k_r$ in $\mathbb{R}^n$.

Example. A point in $\mathrm{Fl}(1, 2; 3)$.

**How can we represent flags
with polynomial equations?**



The Many Lives of Flag Varieties: Stiefel Coordinates

Definition. The Stiefel manifold $V_{k,n}$ is the set of orthonormal k -frames

$$V_{k,n} = \{Z \in \mathbb{R}^{n \times k} : Z^T Z = \text{Id}_k\}.$$

The orthogonal group $O(n)$ is $V_{n,n}$.

Theorem (F.-Hoşten, 2025).

$$\dim(V_{k,n}) = \binom{n}{2} - \binom{n-k}{2} \qquad I(V_{k,n}) = \langle Z^T Z - \text{Id}_k \rangle$$

The ideal $I(V_{k,n})$ is a complete intersection. When $k < n$, $I(V_{k,n})$ is prime.

See also: *The Degree of Stiefel Manifolds* by Brysiewicz and Gesmundo.

The Many Lives of Flag Varieties: Stiefel Coordinates

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The orthogonal group $O(n)$ is $V_{n,n}$.

- $\text{Gr}(k, n) = V_{k,n}/O(k)$
- $\text{Fl}(k_1, \dots, k_r; n) = V_{k,n}/O(k_1) \times O(k_2 - k_1) \times \dots \times O(k_r - k_{r-1})$

Example. $\text{Fl}(1,2; 3) \cong V_{2,3}/O(1)^2$

$$Z = (Z_1 \ Z_2) = \begin{pmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \\ z_{31} & z_{32} \end{pmatrix}$$

The Many Lives of Flag Varieties: Projection Coordinates

A linear subspace $W \subseteq \mathbb{R}^n$ is uniquely determined by the orthogonal projection onto W .

$$\text{pGr}(k, n) = \{P \in \text{Sym}(\mathbb{R}^n) : P^2 = P, \text{trace}(P) = k\}$$

Example. $\text{Fl}(1, 2; 3)$ $Z = (Z_1 \ Z_2) = \begin{pmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \\ z_{31} & z_{32} \end{pmatrix}$

$$P_1 = Z_1 Z_1^T$$

projects onto W_1

$$P_2 = Z Z^T$$

projects onto W_2

$$P_2 P_1 = P_1$$

The Many Lives of Flag Varieties: Projection Coordinates

Theorem (F.-Hoşten, 2025). The projection flag variety $\text{pFl}(k_1, \dots, k_r; n)$ is smooth and has prime ideal

$$\langle P_i P_{i-1} - P_{i-1} : 2 \leq i \leq r \rangle + \langle P_i^2 - P_i, \text{trace}(P_i) - k_i : 1 \leq i \leq r \rangle$$

Here $P_1, \dots, P_r$ are symmetric $n \times n$ matrices. The ambient ring has $r \binom{n+1}{2}$ generators.

See also: “Optimization on Flag Manifolds” by Ye, Wong, and Lim

“The Two Lives of the Grassmannian” by Devriendt, F., Reinke, and Sturmfels

The Many Lives of Flag Varieties: Isospectral Coordinates

Goal: represent points in the flag with symmetric matrices.

Example. $\text{Fl}(1,3;4) \cong V_{3,4}/\text{O}(1) \times \text{O}(2) \cong \text{O}(4)/\text{O}(1) \times \text{O}(2) \times \text{O}(1)$
 $Z = (Z_1 \ Z_2 \ Z_3) \mapsto \tilde{Z} = (Z_1 \ Z_2 \ Z_3 \ Z_4)$

Fix $c_1 > c_2 = c_3 > c_4$.

$$\left\{ \tilde{Z} \begin{pmatrix} \boxed{c_1} & & & \\ & \boxed{c_2} & & \\ & & \boxed{c_3} & \\ & & & \boxed{c_4} \end{pmatrix} \tilde{Z}^T : \tilde{Z} \in \text{O}(4)/\text{O}(1) \times \text{O}(2) \times \text{O}(1) \right\} = \{ Q \in \text{Sym}(\mathbb{R}^n) : Q \text{ has spectrum } (c_1, c_2, c_3, c_4) \}$$

The fact that the set of isospectral matrices parameterizes flag varieties was first observed by Ye and Lim in *Simple Matrix Models for the Flag, Grassmann, and Stiefel Manifolds*.

The Many Lives of Flag Varieties: Isospectral Coordinates

Theorem (F.-Hoşten, 2025). Let $\text{Fl}(k_1, \dots, k_r; n)$ be a flag variety and let X be a symmetric matrix of unknowns. Given a generic choice of $c_1, \dots, c_n$ satisfying $c_{k_j+1} = \dots = c_{k_{j+1}+1}$ for $j = 0, \dots, r$, the variety $\text{Fl}_{\mathbf{c}}(k_1, \dots, k_r; n)$ is smooth and its prime ideal is

$$\left\langle \prod_{j=1}^r (X - c_{k_j} \text{Id}_n), \text{trace}(X) - \sum_{j=1}^n c_j \right\rangle.$$

Example. If $r = 1$, $c_1 = \dots = c_{k_1} = 1$, and $c_{k_1+1} = \dots = c_n = 0$, then

$$\tilde{Z} \text{diag}(1, \dots, 0) \tilde{Z}^T = ZZ^T = P \longrightarrow \text{Fl}_{\mathbf{c}}(k_1; n) = \text{pGr}(k_1, n).$$

The Many Lives of Flag Varieties

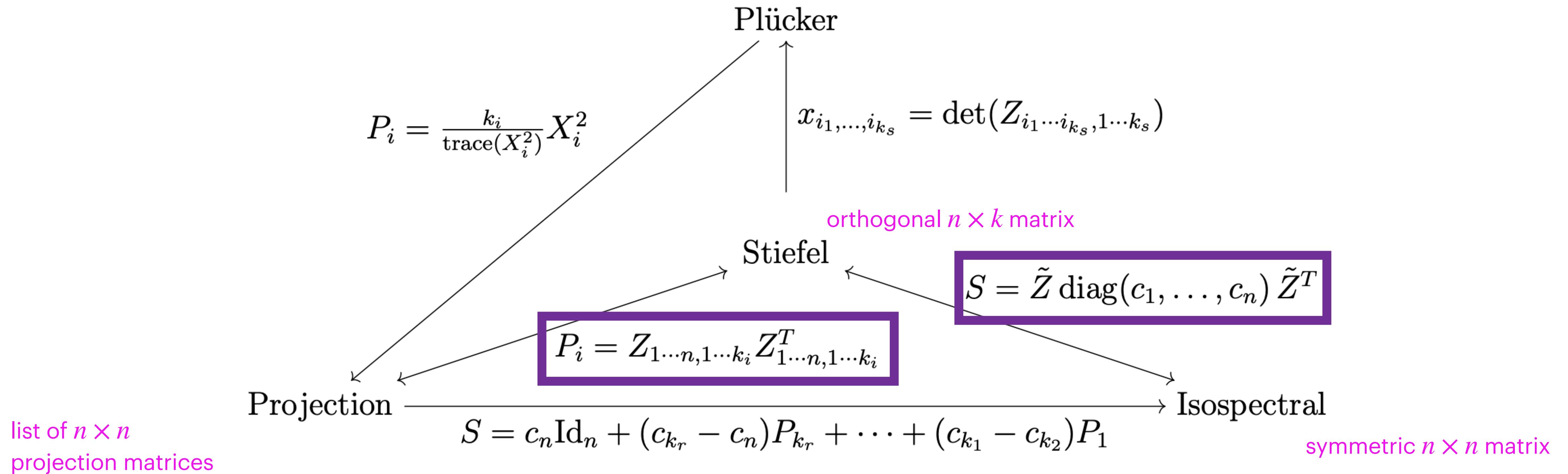


Figure 1: Diagram explaining how to move from one life of the flag variety to another. If $A \rightarrow B$ in the diagram, the edge label explains how to write the B coordinates in terms of the A coordinates. Two of the arrows are bidirectional, meaning that one direction comes from matrix multiplication and the other comes from a matrix factorization.

Algebraic Degree of an Optimization Problem

Optimization Problem

optimize $f(\mathbf{x})$
subject to $G(\mathbf{x}) = 0$



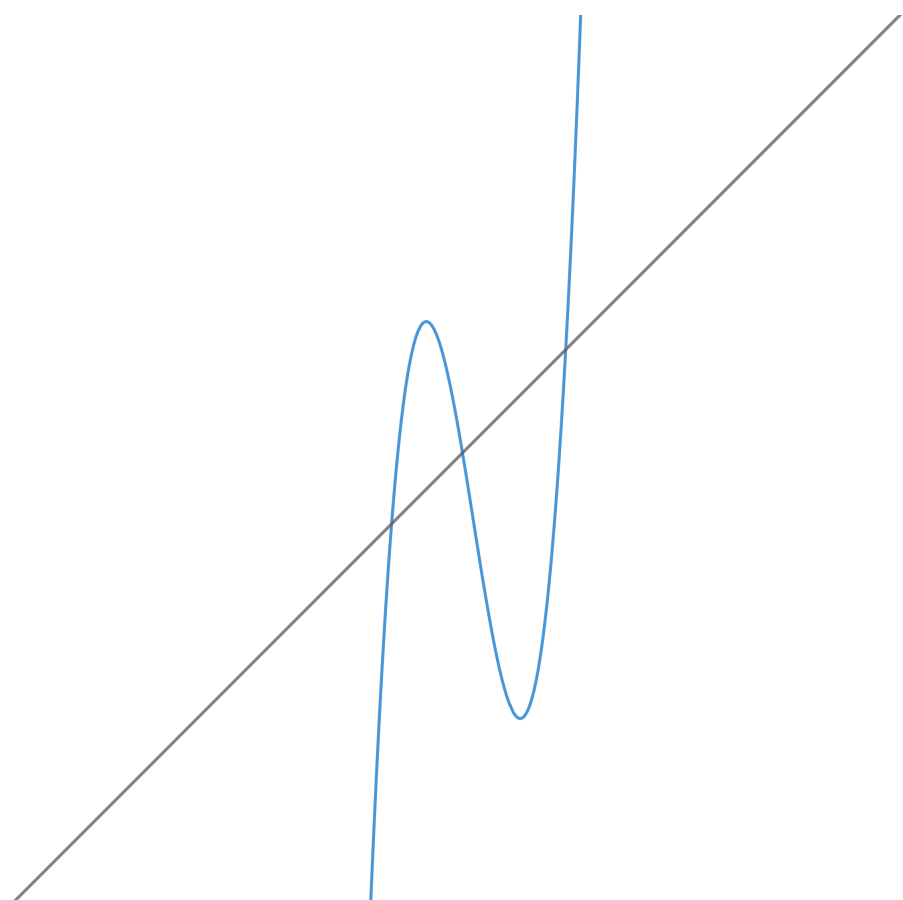
Critical Points

$\text{rank} \left(\text{Jac}(G(\mathbf{x})) \mid \nabla f(\mathbf{x}) \right) = \text{rank} \text{Jac}(G(\mathbf{x}))$
 $G(\mathbf{x}) = 0$

Definition. The *algebraic degree* of an optimization problem is the *number of critical points*. *often 0-dimensional*

When the variety is not zero dimensional, its degree can still give an idea of the complexity of the problem.

The algebraic degree of a problem is a proxy for the difficulty of correctly solving the problem.



Multi-Eigenvalue Problem

Let A be real, symmetric $n \times n$ matrix.

Goal: compute an $n \times k$ matrix $Z \in V_{k,n}$ such that the columns of Z are eigenvectors of A .

$$\max_{Z \in V_{k,n}} \text{trace}(Z^T A Z)$$

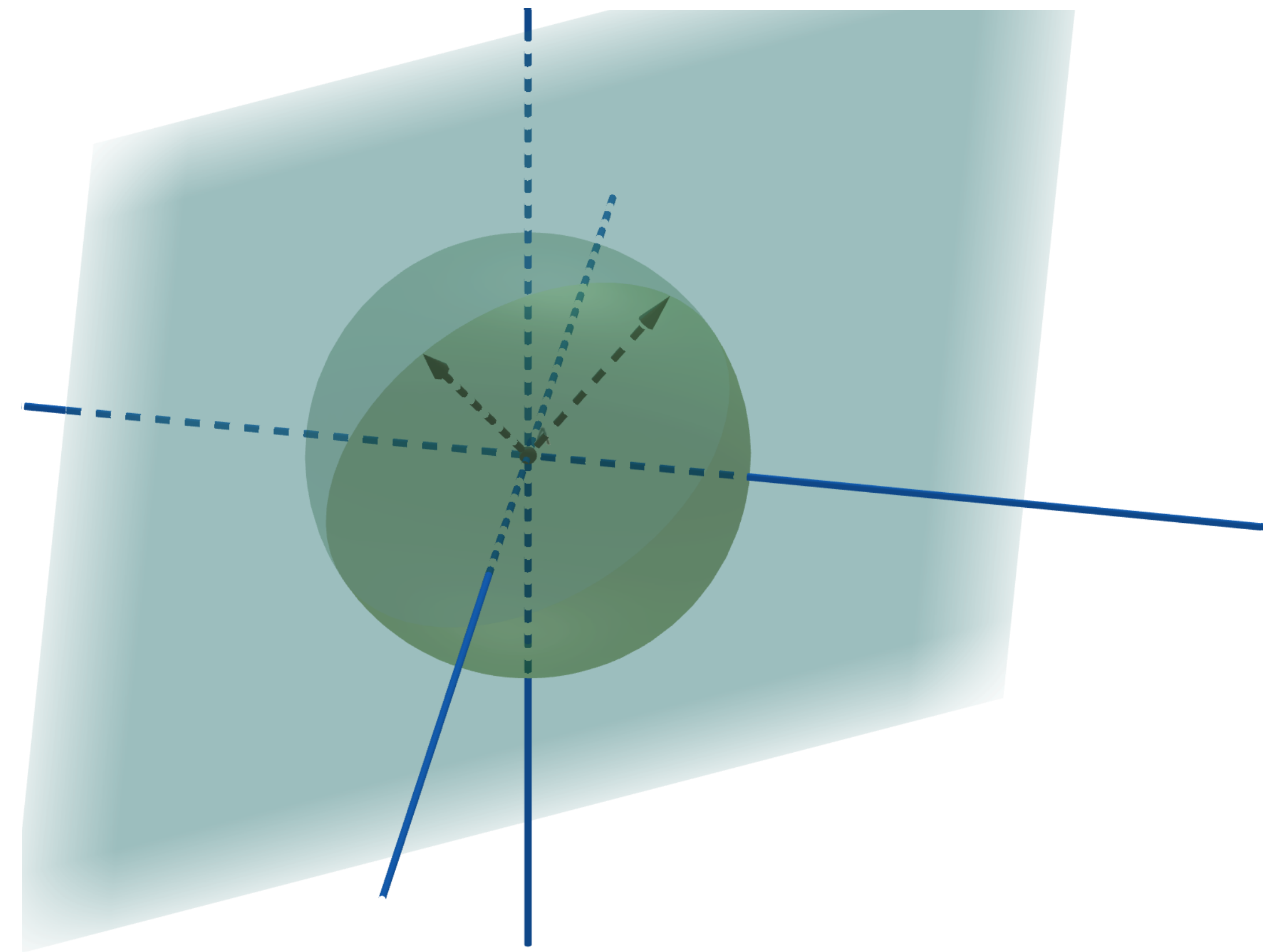
Critical Points of the Multi-Eigenvalue Problem

The optimization problem $\max_{Z \in V_{k,n}} \text{trace}(Z^T A Z)$ is **invariant** under the action of $O(k)$.

Let $Q \in O(k)$.

$$\text{trace}(Q^T Z^T A Z Q) = \text{trace}(Z^T A Z Q Q^T) = \text{trace}(Z^T A Z)$$

$$Z^T Z = \text{Id}_k \implies Q^T Z^T Z Q = Q^T Q = \text{Id}_k$$



Critical Points of the Multi-Eigenvalue Problem

Theorem (F., Hoşten 2025). Let A be a generic real symmetric $n \times n$ matrix and let $Z \in V_{k,n}$. The algebraic set of complex critical points of the eigenvalue optimization problem is

$$\bigsqcup_{\{i_1, \dots, i_k\} \in \binom{[n]}{k}} \{[u_{i_1} \ u_{i_2} \ \cdots \ u_{i_k}] Q : Q \in O(k)\}$$

where $q_1, \dots, q_n$ is an orthonormal eigenbasis of A . This algebraic set is a disjoint union of $\binom{n}{k}$ irreducible varieties isomorphic to $O(k)$, and hence its dimension is equal to $\dim(O(k))$ and its degree is equal to $\deg(O(k)) \cdot \binom{n}{k}$.

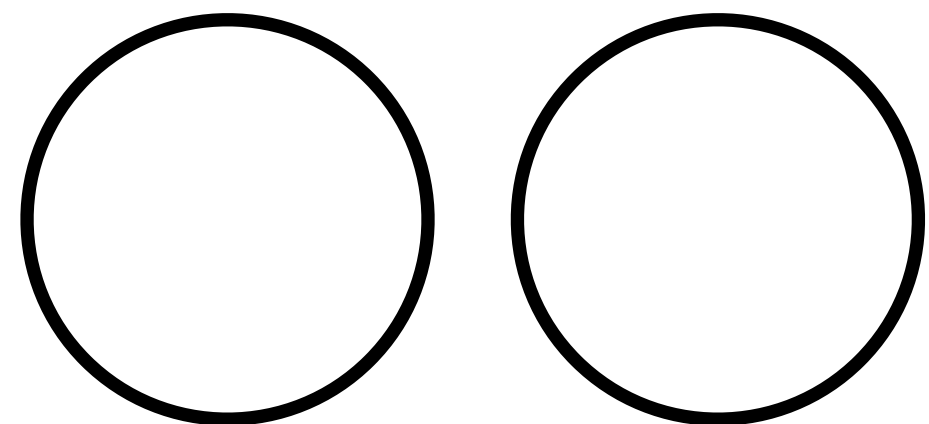
Multi-Eigenvalue Problem in Projection Coordinates

$$\max_{Z \in V_{k,n}} \text{trace}(Z^T A Z)$$

$$\max_{Z \in V_{k,n}} \text{trace}(A Z Z^T)$$

$$Z Z^T \mapsto P$$

$$\max_{P \in \text{pGr}(k,n)} \text{trace}(A P)$$



$$\{i_1, \dots, i_k\}$$



$$\{i_1, \dots, i_k\}$$

Multi-Eigenvalue Problem in Projection Coordinates

Theorem (F.-Hoşten, 2025). Let A be a generic real symmetric $n \times n$ matrix. The optimization problem

$$\max_{P \in \text{pGr}(k,n)} \text{trace}(AP)$$

has critical point set

$$\left\{ [u_{i_1} \ u_{i_2} \ \cdots \ u_{i_k}] [u_{i_1} \ u_{i_2} \ \cdots \ u_{i_k}]^T \mid \{i_1, \dots, i_k\} \in \binom{[n]}{k} \right\}$$

where $u_1, \dots, u_n$ is an orthonormal eigenbasis of A and algebraic degree $\binom{n}{k}$.

Corollary. The linear optimization degree of $\text{pGr}(k, n)$ is $\binom{n}{k}$.

The linear optimization degree of a variety was introduced in *Linear Optimization on Varieties and Chern Mather Classes* by Maxim, Rodriguez, Wang, and Wu.

Multi-Eigenvalue Problem in Isospectral Coordinates

$$P = ZZ^T = \tilde{Z} \operatorname{diag}(1, \dots, 1, 0, \dots, 0) \tilde{Z}^T$$

$$X = \tilde{Z} \operatorname{diag}(c_1, c_2, \dots, c_n) \tilde{Z}^T$$

$$\max_{P \in \operatorname{pGr}(k, n)} \operatorname{trace}(AP)$$

$$\star \max_{X \in \operatorname{Fl}_{\mathbf{c}}(\mathbf{k}; n)} \operatorname{trace}(AX)$$

Theorem (F.-Hoşten, 2025). The critical points of $\star$ are the points in $\operatorname{Fl}_{\mathbf{c}}(\mathbf{k}; n)$ representing different flag structures on the eigenspaces of A . The degree of $\star$ is

$$\binom{n}{k_1, k_2 - k_1, \dots, n - k_r}.$$

Corollary. The linear optimization degree of $\operatorname{Fl}_{\mathbf{c}}(\mathbf{k}; n)$ is $\binom{n}{k_1, k_2 - k_1, \dots, n - k_r}.$

Heterogeneous Quadratics Minimization Problem

Problem. Fix real symmetric matrices $A_1, \dots, A_k$. How many critical points does the following optimization problem have?

$$\min_{Z \in V_{k,n}} \sum_{i=1}^k Z_i^T A_i Z_i \qquad Z = (Z_1 \ Z_2 \ \cdots \ Z_k)$$

	$n = 2$	$n = 3$	$n = 4$	$n = 5$	$n = 6$	$n = 7$	$n = 8$	$n = 9$
$k = 2$	8	40	112	240	440	728	1120	1632
$k = 3$		80	960	5536	21440	64624		
$k = 4$			1920	57216				

Table 1: Degrees of the heterogeneous quadratics minimization problem for small k, n .

Conjecture. The number of critical points for $k = 2$ is $8 \sum_{j=1}^{n-1} j^2$.

Stiefel & Projection Coordinates

$$V_{k,n} \rightarrow \text{pFl}(1,2,\dots,k;n)$$

$$Z = (Z_1 \ Z_2 \ \dots \ Z_k) \mapsto (Z_1 Z_1^T, \ Z_1 Z_1^T + Z_2 Z_2^T, \ \dots, \ Z Z^T) = (P_1, P_2, \dots, P_k)$$

$$\min_{Z \in V_{k,n}} \sum_{i=1}^k Z_i^T A_i Z_i$$

$$\min_{Z \in V_{k,n}} \sum_{i=1}^k \text{trace}(A_i Z_i Z_i^T)$$

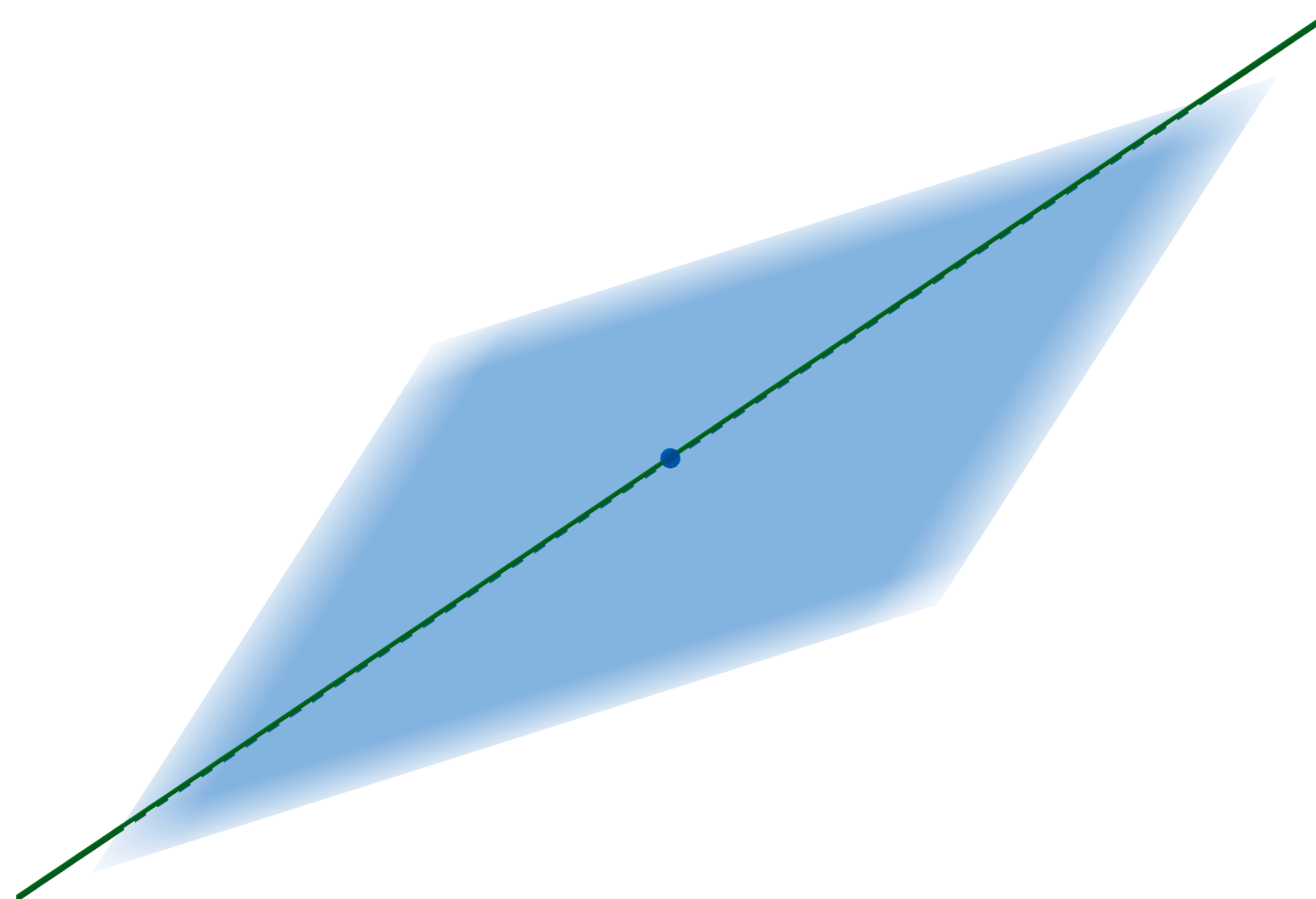


$$\min_{(P_1, \dots, P_k) \in \text{pFl}(\mathbf{k}; n)} \sum_{i=1}^k \text{trace}(B_i P_i)$$

$$\mathbf{k} = (1, 2, \dots, k)$$

$$\frac{1}{2^k} \text{ Algebraic degree of } \min_{Z \in V_{k,n}} \sum_{i=1}^k Z_i^T A_i Z_i = \text{Algebraic degree of } \min_{(P_1, \dots, P_k) \in \text{pFl}(\mathbf{k}; n)} \sum_{i=1}^k \text{trace}(B_i P_i) = \text{Linear optimization degree of pFl}(\mathbf{k}; n)$$

Thank you!



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The Many Lives of Flag Varieties: Plücker Coordinates

Theorem. The variety $\mathrm{Fl}(k_1, \dots, k_r; n) \subseteq \mathbb{P}^{\binom{n}{k_1}-1} \times \dots \times \mathbb{P}^{\binom{n}{k_r}-1}$ in Plücker coordinates is defined by the prime ideal generated by the quadrics

$$x_{i_1, \dots, i_{k_s}} x_{j_1, \dots, j_{k_t}} - \sum x_{i'_1, \dots, i'_{k_s}} x_{j'_1, \dots, j'_{k_t}}$$

for every pair $1 \leq s < t \leq r$ and where the sum is over all (i', j') obtained by exchange the first m of the j -subscripts with m of the i -subscripts while preserving their order.